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6. Column Space and Nullspace *Linear Algebra Done Right* Book Review 5. ~~Transposes, Permutations, Spaces R^n~~ 7. Solving Ax = 0: Pivot Variables, Special Solutions 15. *Projections onto Subspaces*

30. Linear Transformations and Their Matrices *Strang Linear Algebra Instructors Manual*

Solution Manual for: Linear Algebra by Gilbert Strang John L. Weatherwax? January 1, 2006 Introduction A Note on Notation In these notes, I use the symbol ? to denote the results of elementary elimination matrices used to transform a given matrix into its reduced row echelon form. Thus when looking for the eigenvectors for a matrix like A= 0 0 2 0 1 0 0 0 2 rather than say, multiplying Aon ...

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The row picture for T A = I has 3 perpendicular planes x = 2 and y = 3 z = 4. Those are perpendicular to the x and y and z axes: z = 4 is a horizontal plane at height 4. The column vectors are i = (1,0,0) and j = (0,1,0) and k = (0,0,1). Then b = (2,3,4) is the linear combination 2i + 3j + 4k.

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the linear transformation T. Key point: Column space of matrix matches range of transformation. 8 We don't know T(w) unless the 's are the same as the v's. In that case the matrix is A. 2. Rank of A = 2 = dimension of the range of T. The outputs v (column space) match the outputs T(v) (the range of T). The "output space" W is like Rm ...

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The nonzero rows of U come from edges 1 and 3 in a tree. The zero row comes from the loop (all 3 edges). 4 For the matrix in Problem 3, Ax = b is solvable for b = (1,1,0) and not solvable for b = (1,0,0). For solvable b (in the column space), b must be orthogonal to y = (1,?,1); that combination of rows is the zero row, and b

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Solutionsto Exercises 153 8 This P is invertible and unitary. 2 = 0 0 ? 1 ? 1 0 0 ? 1 0 , P 3 = ? i ? i ? i = ? i l. Then P 100 = (? i) 3 3 P = ? i P. The eigenvalues of P are the roots of ? 3 = ? i, which are i and ie 2 ? i / 3 and ie 4 ? i / 3. 9 One unit eigenvector is certainly x 1 = (1 , 1 1) with ? 1 = i. The other eigenvectors

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The combinations give (a) a line in T R 3 (b) a plane in R 3 (c) all of R 3. 2 v + w = (2,3) and ? = (6 1) will be the diagonals of the parallelogram with v and w as two sides going out from (0,0). 3 This problem gives the diagonals v + w and ? of the parallelogram and asks for the sides: The opposite of Problem 2.

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46 Solutionsto Exercises 10 The only subspaces are (a) the plane with b 1 = 2 (d) the linear combinations of v and w (e) the plane with b 1 + b 2 + b 3 = 0. 11 (a) All matrices a b 0 0 (b) All matrices a a 0 0 (c) All diagonal matri-ces. 12 For the plane x + y + 2z = 4, the sum of (4 , 0 0) and (0 4 is not on the plane. (The key is that this plane does not go through (0,0,0).)

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The combinations give (a) a line in R 3 (b) a plane in R 3 (c) all of R 3. 2 v + w = (2,3) and ? = (6 1) will be the diagonals of the parallelogram with v and w as two sides going out from (0,0). 3 This problem gives the diagonals v + w and ? of the parallelogram and asks for the sides: The opposite of Problem 2. In this example v = (3,3) and w = (2,2).

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